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Solution 1.12 Since point G is the center of mass of the body, this point would be used to carry out an angular momentum balance based on Eq. (1.17). One cannot use Eq.

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Solutions to Exercises - Chapter 1. 1.17 In the system shown in Figure 1.6, if the mass of the pendulum is m , the length of the pendulum is r , and the rotary inertia of the disc about the point ...

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Solutions to Exercises - Chapter 1. Solution 1.14 We make use of Eq. (1.23) to determine the system kinetic energy. Note that the velocity of the center of mass G can be obtained as in the ...

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Solutions to Exercises - Chapter 1. 1.13 Consider the rigid body shown in Figure E1.13. This body has a mass m and rotary inertia J_G about the center of mass G .

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Making use of the velocity determined in the solution of Exercise 1.5, we find that $T_{slider} = \frac{1}{2} M v^2 + \frac{1}{2} I_G \omega^2 = \frac{1}{2} M v^2 + \frac{1}{2} I_G \left(\frac{v}{r}\right)^2 = \frac{1}{2} \left(M + \frac{I_G}{r^2}\right) v^2$ and, therefore, $T = \frac{1}{2} \left(M + \frac{I_G}{r^2}\right) v^2$

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the numerical solutions and complementing analytical solutions. The algorithms for generating numerical solutions should be presented external to the chapters, as they tend to break the flow of the material being presented. (The MATLAB algorithms used to construct and generate all solutions can be found at the publisher's web site for this ...

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p p p pZ Z D Z Z D12 1.5 In Figure E1.5, a slider of mass M_r is located on a bar whose angular displacement in the plane is described by the coordinate T .

Solutions to Exercises Chapter 1 - test bank and solution

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